

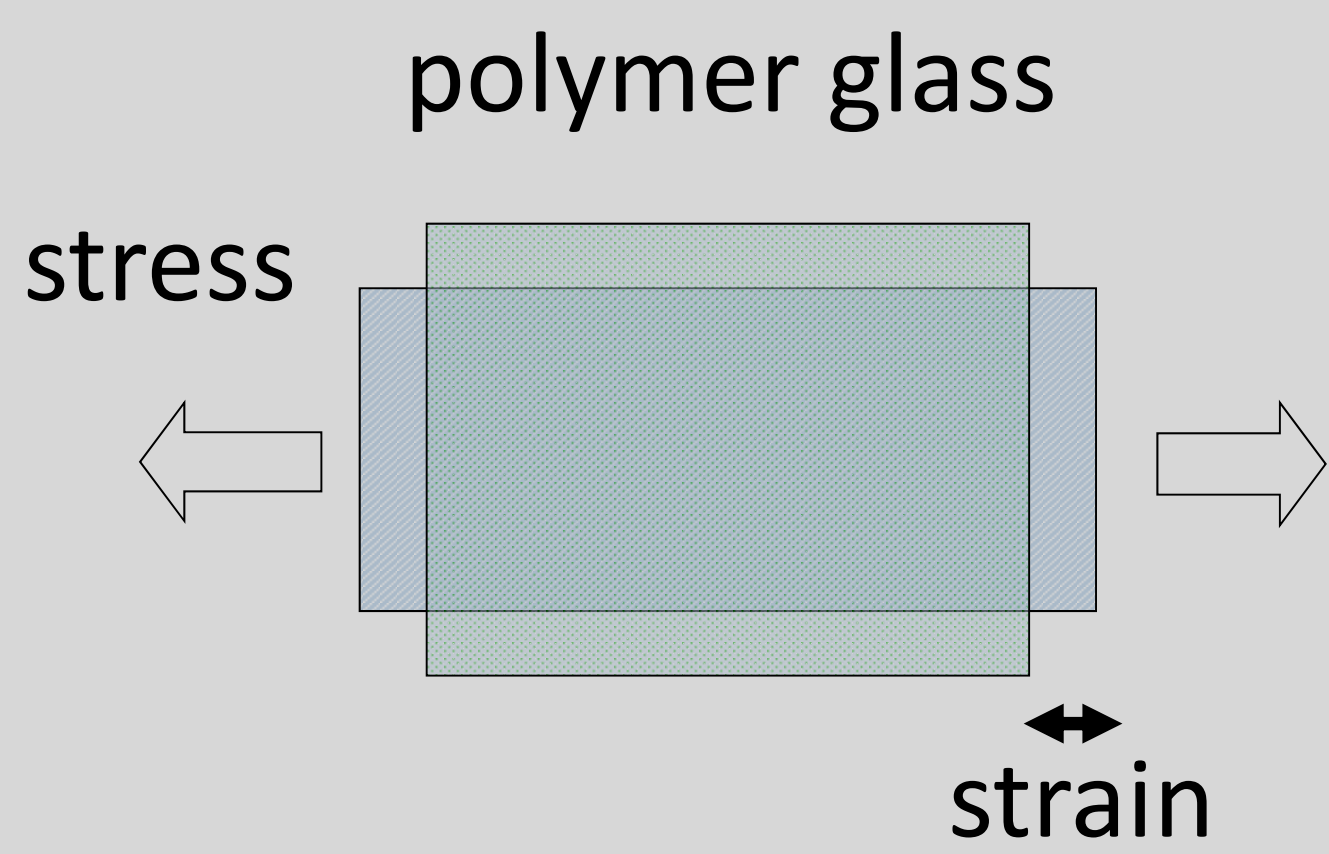
Theory of nonlinear creep under large deformation in polymer glasses

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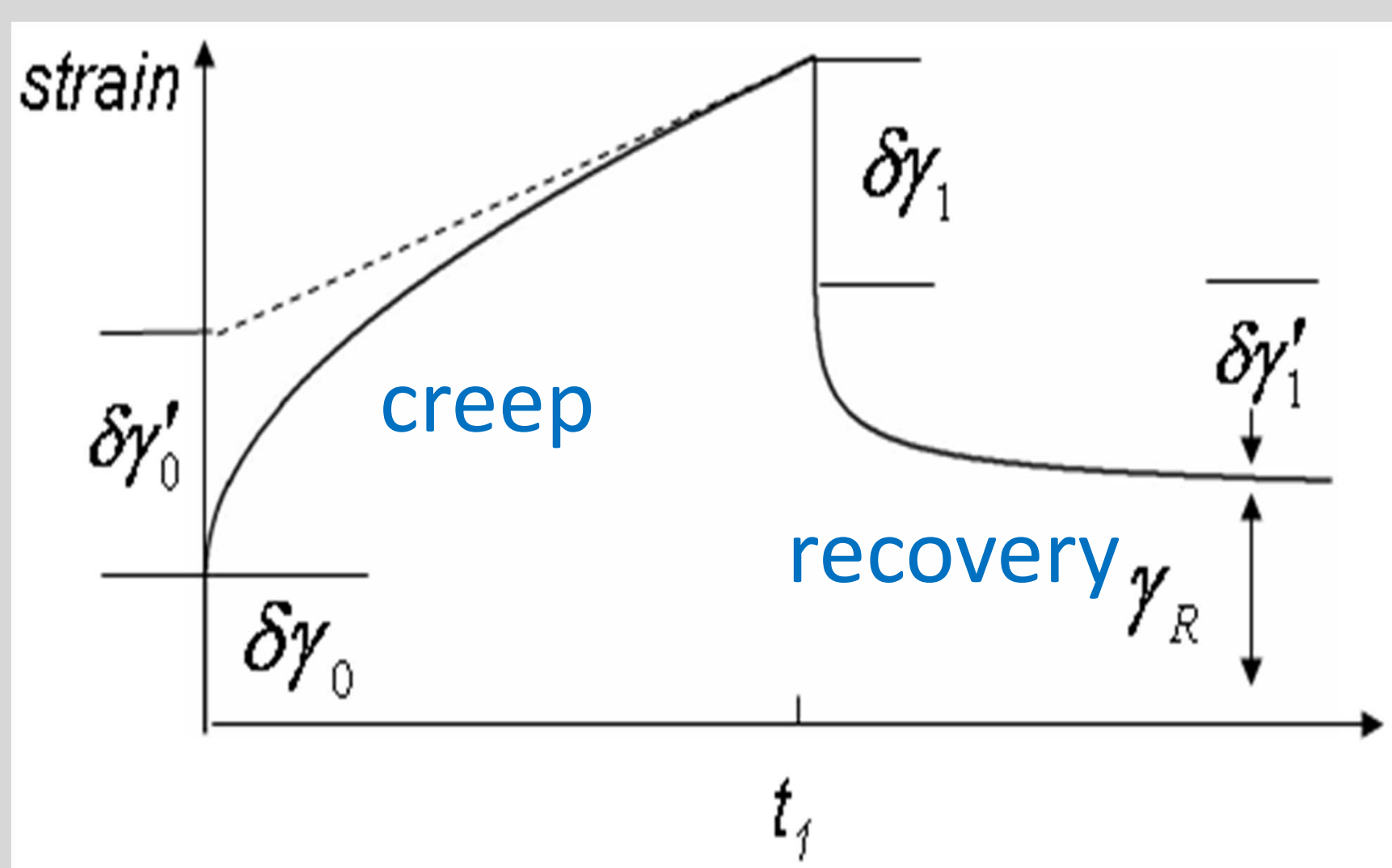
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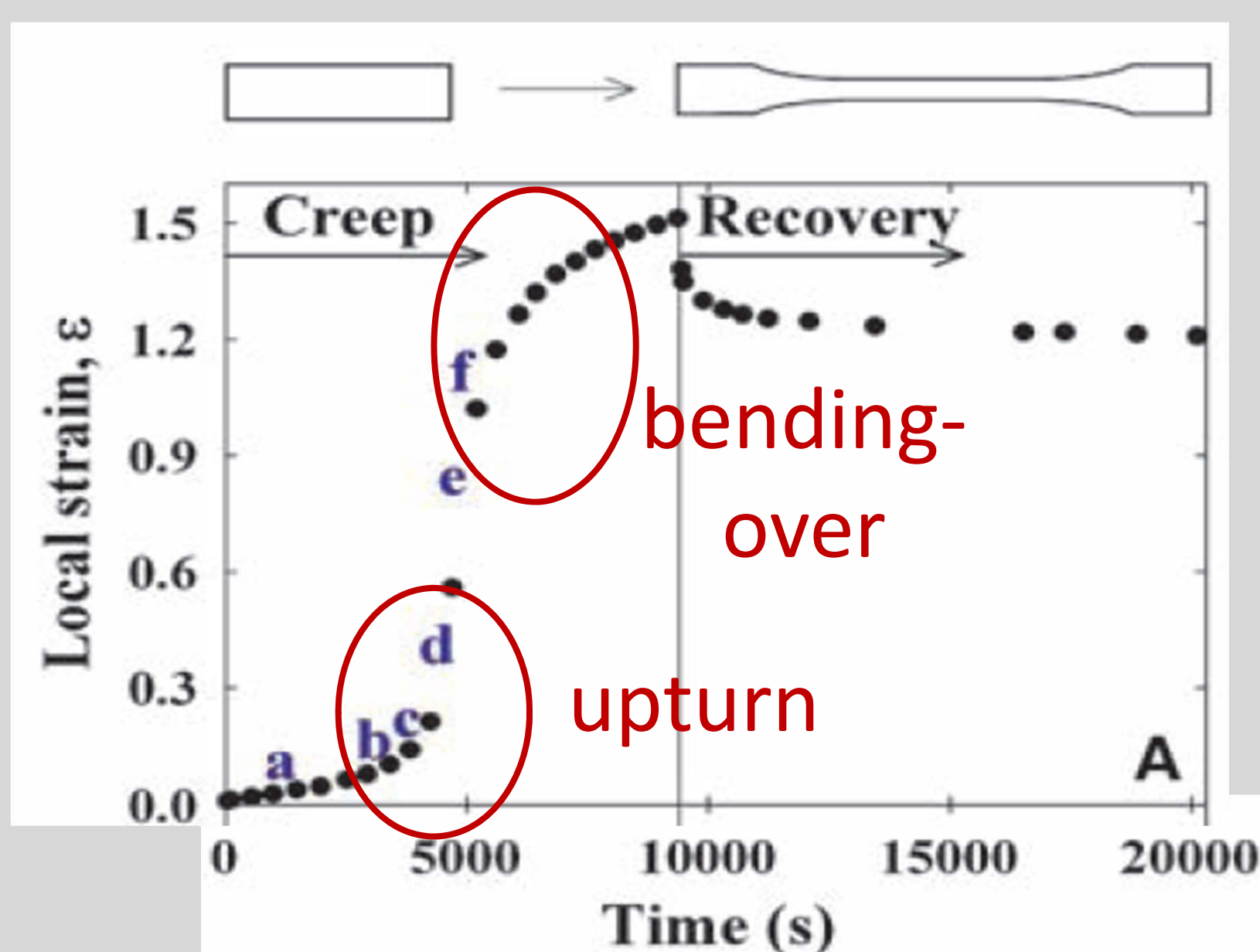
Goal



- Creep is defined by the time dependence of strain at constant stress



- At low stress, the typical ideal creep curve grows monotonically and gradually bends down approaching the steady flow state (constant strain rate) after an instantaneous jump



- But, at large stress and/or deformation, a dramatic upturn occurs, and followed by a bending-over at very large strain

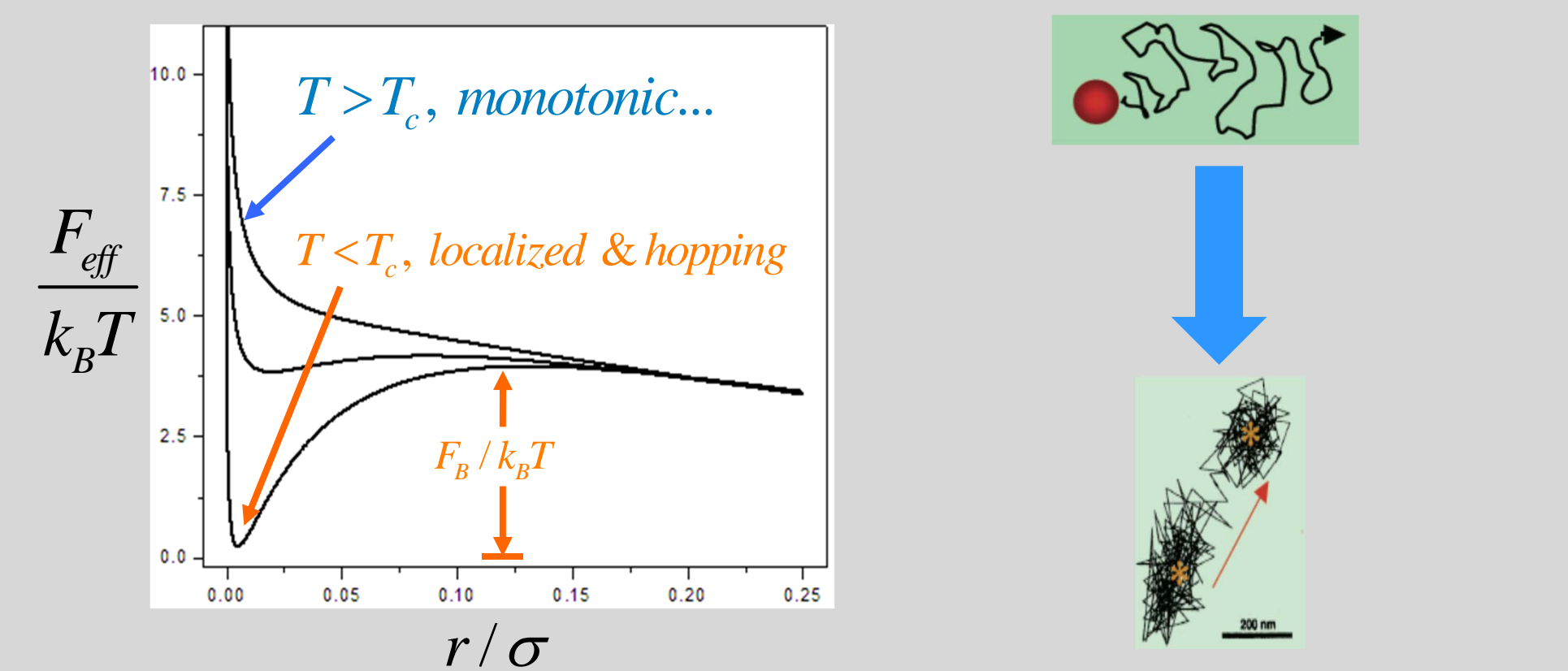
- What's the origin of the upturn and bending-over?
- What causes the dynamics change during these processes?
- How to model the creep response?

Microscopic theory of glassy dynamics

- Dynamical "free energy" for single-segment movement:

$$\zeta_s \frac{\partial r(t)}{\partial t} = -\frac{\partial}{\partial r} F_{eff}(r(t)) + \eta(t)$$

$$F_{eff}(r) = -3k_B T \ln(r) - k_B T \int \frac{d\bar{q}}{(2\pi)^3} \rho C^2(q) S(q) [1 + S^{-1}(q)]^{-1} e^{-q^2 r^2 (1 + S^{-1}(q)) / 6}$$



- State variable under Gaussian thread model

$$S_0 = S(q=0)$$

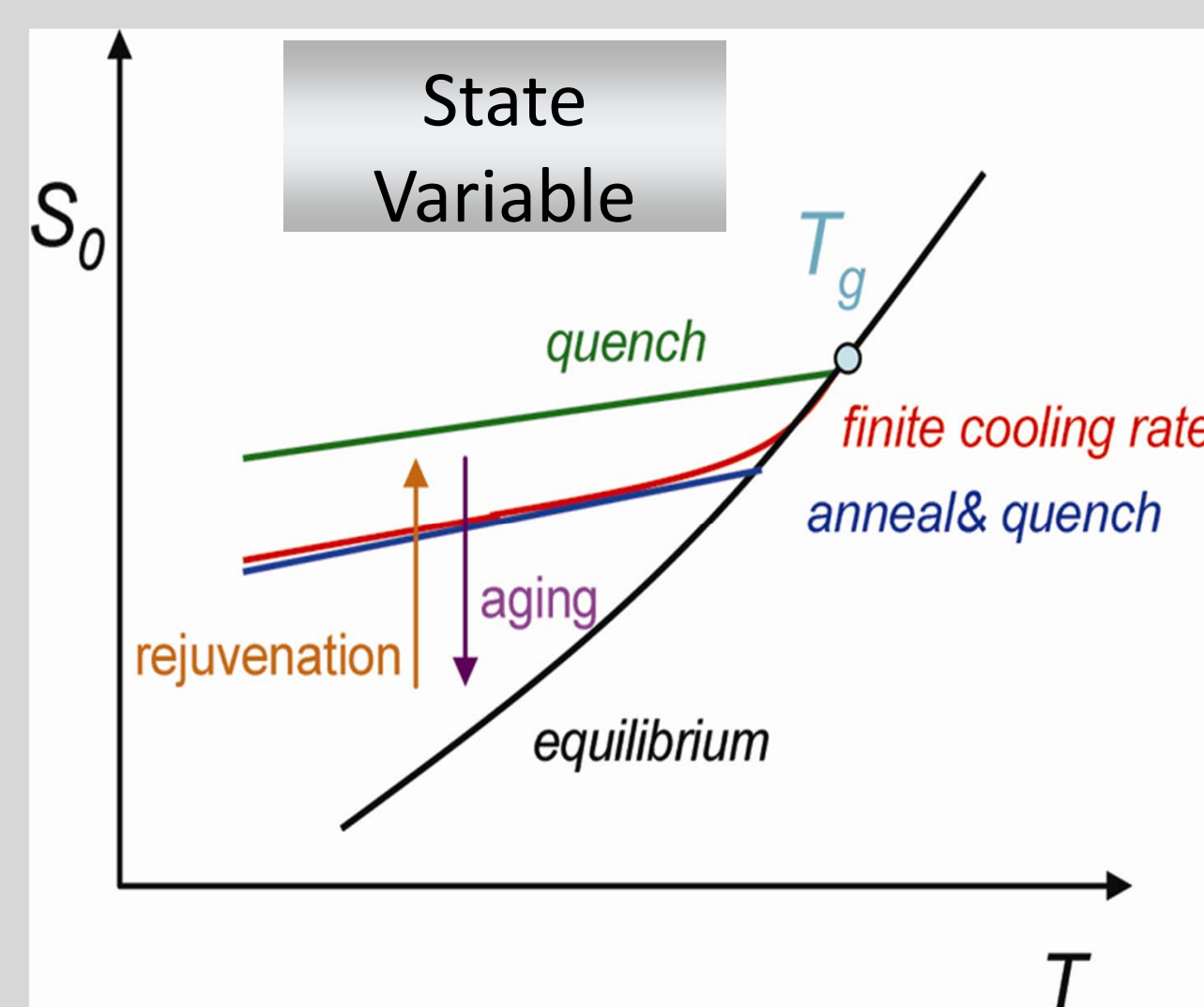
determines

Mechanical and Dynamical properties:

Elastic modulus: E'

Alpha relaxation time: $\tau_\alpha(T) = \tau_0(T) e^{a_c F_B / k_B T}$

Model of aging and rejuvenation



aging

rejuvenation

$$\frac{dS_0}{dt} = -\frac{S_0 - S_{0,l}}{\tau_\alpha(S_0, 0)} + \psi(S_{0,g} - S_0) \cdot \tau \cdot \frac{\tau}{E'(S_0, \tau) \tau_\alpha(S_0, \tau)}$$

plastic strain rate

Constitutive equation of nonlinear mechanical response

- Generalized Maxwell Model:

$$\dot{\gamma} = \frac{d\tau}{dt} \frac{1}{E'(\tau)} + \frac{\tau}{E'(\tau) \tau_\alpha(\tau)}$$

elastic strain rate *plastic strain rate*

- Nonexponential decay:

$$\tau(t) = \int_0^t dt' E'(\tau(t')) e^{-\left[\int_0^{t'} dt'' \tau_\alpha^{-1}(\tau(t'')) \right]^{\beta_K}} \dot{\gamma}(t')$$

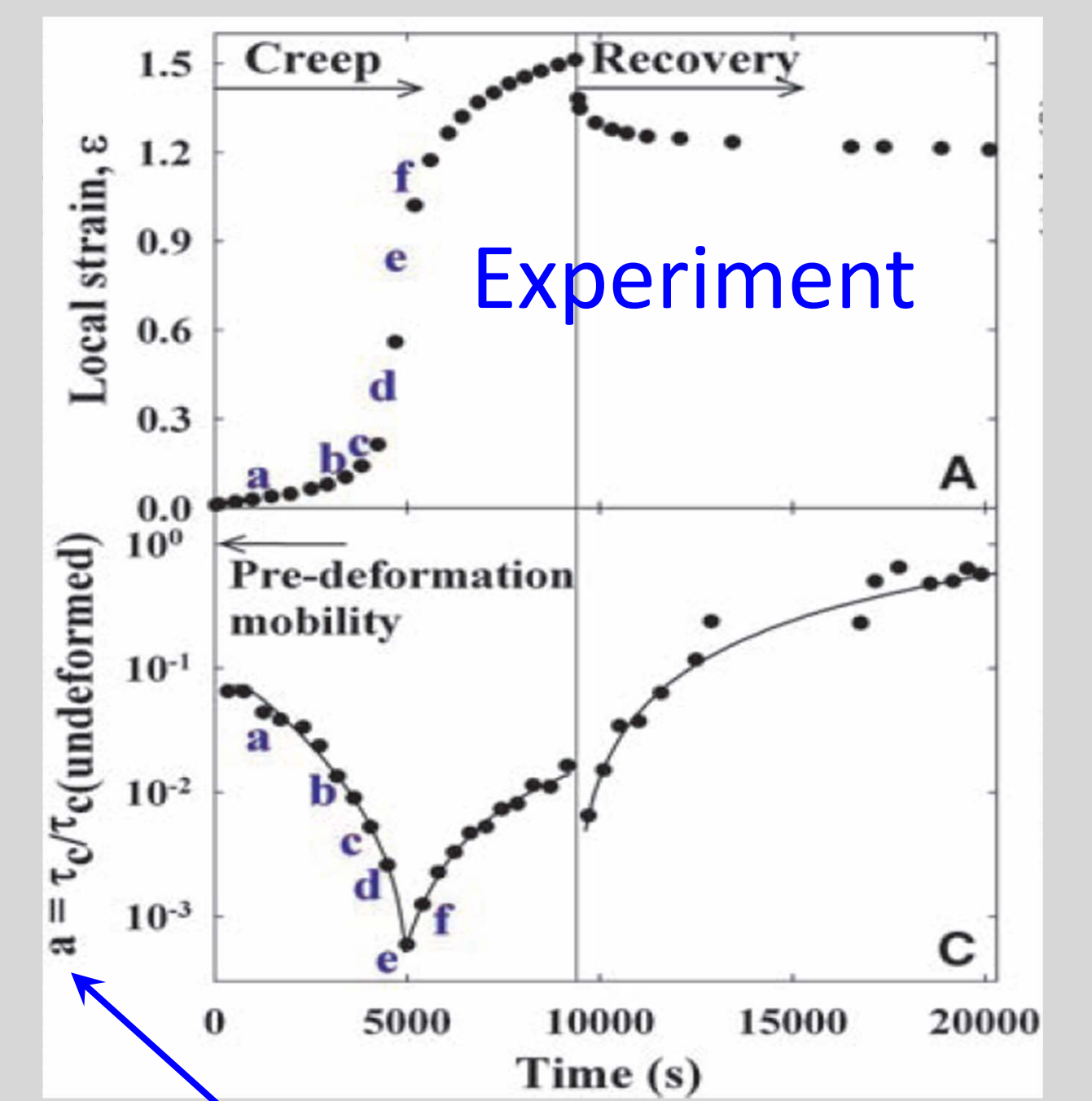
β_K : related to heterogeneity

- Strain hardening at large deformation
State variable decreases for stretched chain

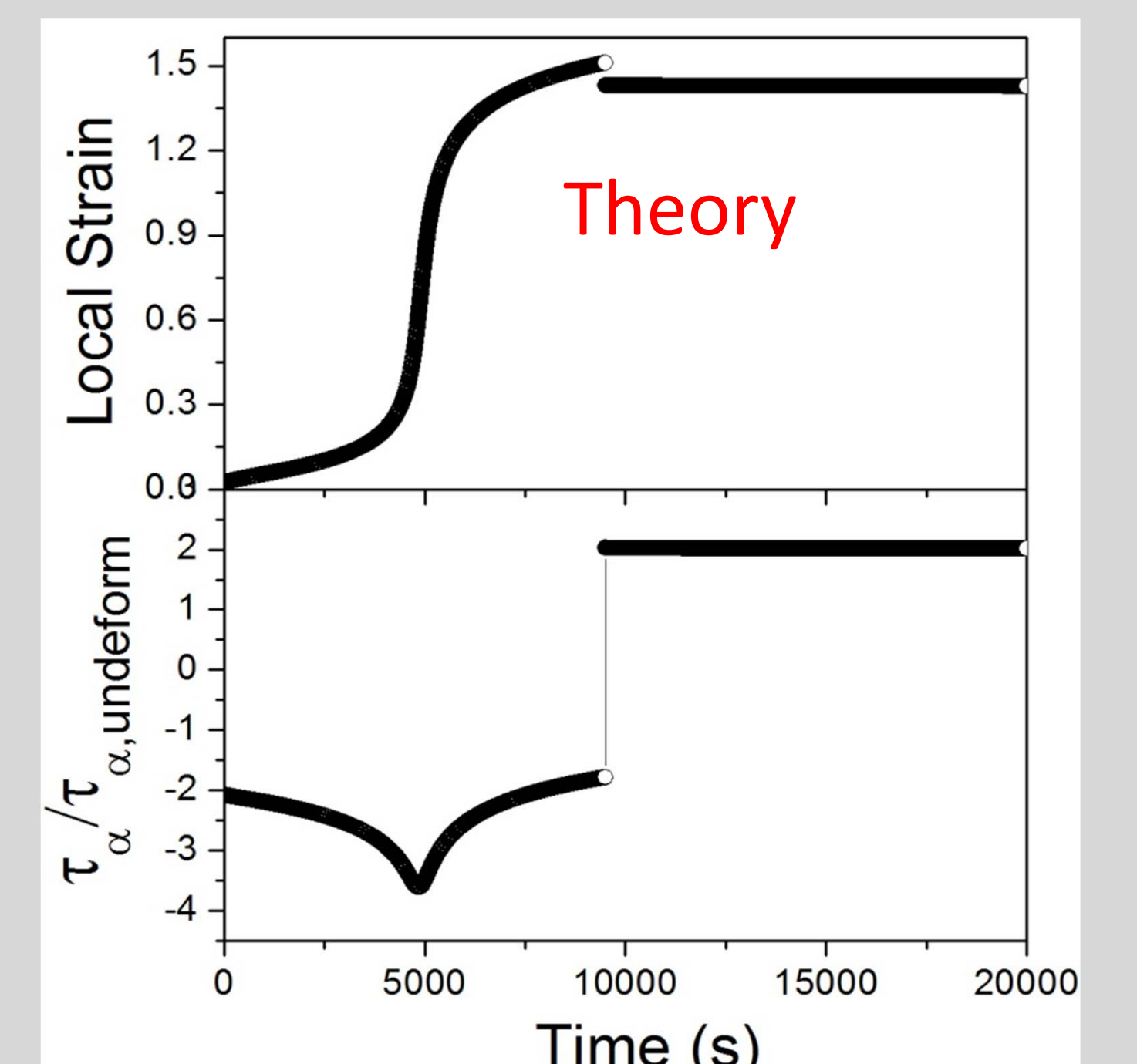
$$\frac{S_{0,eff}}{S_0} \approx \frac{1}{1 + \sqrt{\frac{S_0}{N_x} \frac{1}{4} (\lambda^2 + \frac{2}{\lambda} - 3)}}$$

$\lambda = e^\gamma$

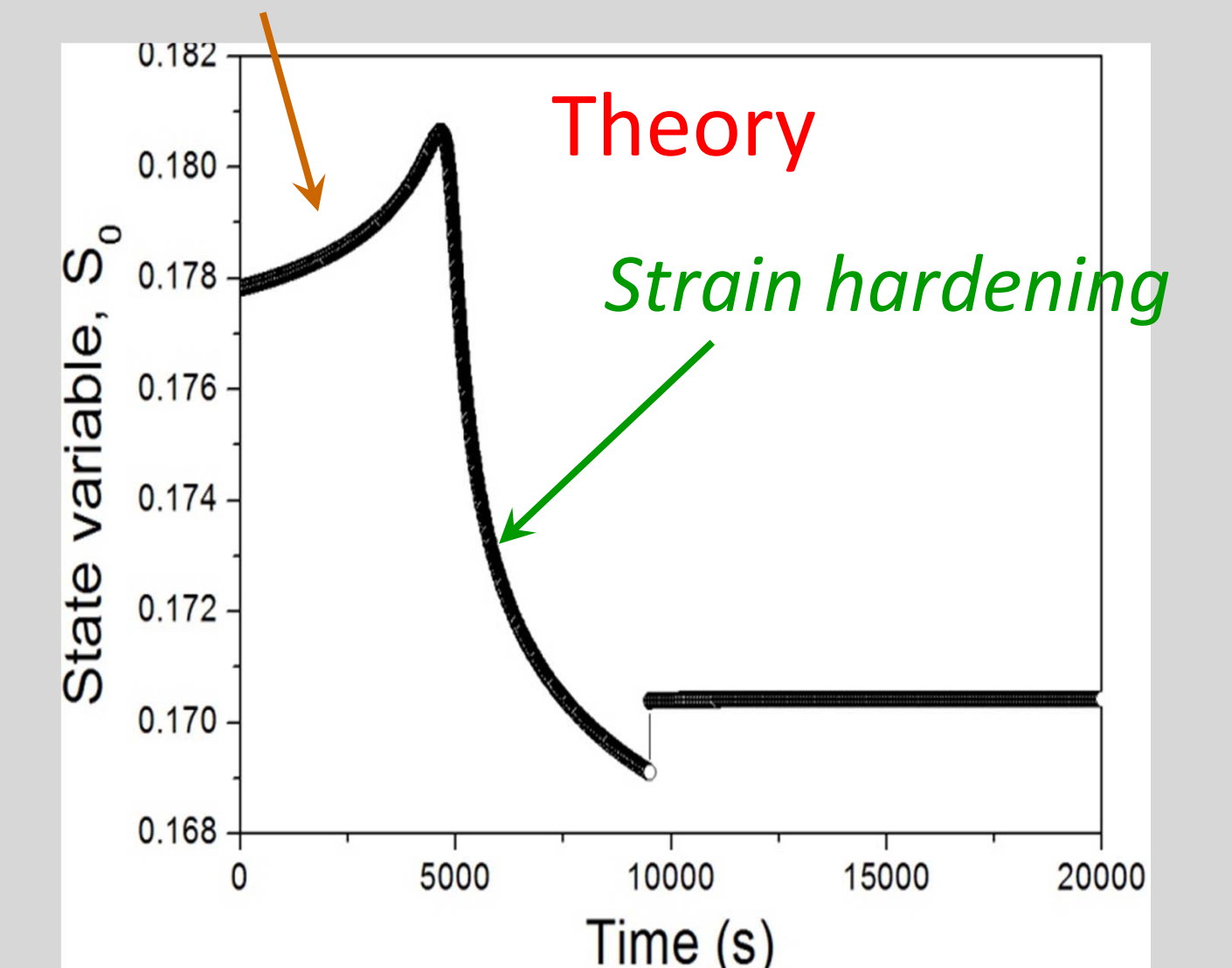
Results: Creep at large stress



Shift factor (relaxation time)



rejuvenation



Conclusion

- The *upturn* behavior is caused by *rejuvenation* process.
- The *bending-over* happening at very large deformation is due to *strain hardening*.
- Strain response and relaxation time are well predicted except for the recovery process because of the lack of relaxation mechanism of stretched chain in the theory.